

Variable Frequency Drives CFW09 Vectrue Inverter

The WEG CFW09 Series of Variable Frequency Drives incorporates the world's most advanced technology in drives for three-phase AC induction motors. The Vectrue Technology[™] represents a significant inovation, allowing this generation of WEG VFD's to combine Volts/Hertz, Sensorless Vector and Closed Loop Vector (with encoder) control techniques all in one product. In addition, WEG's exclusive Optimal Braking[™] technology eliminates the need for the dynamic braking resistor in some applications allowing a simpler, more compact and economic solution.

Applications

Fans / Blowers

Compressors

Grizzly Feeders

Cranes and Hoists

Agitators and Mixers

Conveyors

Extruders

Centrifuges

Presses

Saws

Rollout Tables

Pumps

Standard Features

- V/Hz or Sensorless Vector Control via parameter selection
- Self Tuning to motor parameters
 - NEMA 1 Enclosure up to 200HP
 - IP20 "Finger Safe" Enclosure from 250 to 500HP
 - 200-240V or 380-480V input voltage
 - Single or Three-phase input voltage up to 3HP/230V
 - 150% current overload capacity
 - DC bus connections accessible
 - Detachable Smart Keypad with dual display and Copy Function
 - 32 bit RISC microprocessor controlled PWM output
 - 1.25 / 2.5 / 5 / 10 kHz adjustable switching frequency
- Six isolated programmable digital inputs
- Three programmable relay outputs (250Vac / 1A)
- Two isolated programmable analog inputs
- Two programmable analog outputs
- Protective features: Over current, motor overload, drive over temperature, output phase-to-phase and phase-to-ground short circuit, DC bus over and under voltage, power supply under voltage and phase loss and external fault
- Control features: Linear and "S" amp acceleration and deceleration, local/remote control, DC braking, torque boost, motor slip compensation, electronic pot, preset speeds, adjustable V/Hz profile, maximum and minimum adjustable motor speed limits, three skip frequencies, adjustable output current limit, JOG, ride-thru, flying start and PID regulator
- Display readings: Motor speed, frequency, voltage, current and torque, output power (kW), last four faults, drive status, digital and analog I/O status, hours powered and hours running
- Ambient: 32°F (0°C) to 104°F (40°C), 3300 ft (1000m) altitude, 90% humidity, non- condensing

Optional Features

- Closed loop vector control
- Remote keypad with cable and mounting frame
- RS-232 or RS-485 Serial Interface
- On/Off line PC programming with Superdrive
- Fieldbus Comm: Profibus DP, DeviceNet or Modbus RTU*
- Encoder buffered output
- Additional digital and analog I/O
- Dynamic Braking Resistors available for most models
 *Requires optional RS-232 or

RS-485 Interface





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Variable Frequency Drives CFW09

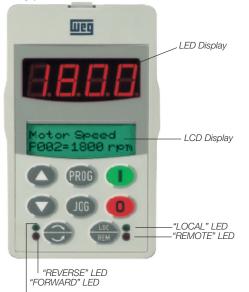
NEMA 1 Enclosure and compact product

otor	Motor		Drive I		Catalog Number	Braking Transistor	Frame	Dimensions (in.)	App. Shpg. Wt. (II
olts	CT*		CT* Y: SINGLE 0				Size	H x W x D	
	1 or 1		1: SINGLE 0		CFW-090006TDZ		1	8.3 X 5.6 X 7.7	9
	2	.0	7		CFW-090007TDZ	YES	1	8.3 X 5.6 X 7.7	9
	3 10		CFW-090007102	160	1	8.3 X 5.6 X 7.7	9		
		FR SLIPPI	Y: THREE-PH				1	0.5 A 3.0 A 1.1	9
	3 13				CFW-090013TDZ		1	8.3 X 5.6 X 7.7	9
	5		16		CFW-090016TDZ	_	2	11.4 X 7.2 X 7.7	15
	7.5		24		CFW-090024TDZ	YES	2	11.4 X 7.2 X 7.7	15
	10		28		CFW-090028TDZ		2	11.4 X 7.2 X 7.7	15
	15		45		CFW-090045TDZ	-	3	15.3 X 8.9 X 10.8	46
	20	25	54	68	CFW-090054TDZ		4	18.7 X 9.8 X 10.8	55
230V	25	30	70	86	CFW-090070TDZ	-	5	21.6 X 13.2 X 10.8	101
	30	40	86	105	CFW-090086TDZ	NO use CFW-09 0XXXTDDB	5	21.6 X 13.2 X 10.8	101
	40	50	105	130	CFW-090105TDZ	- BELOW	6	26.6 X 13.2 X 11.8	135
	50		130	150	CFW-090130TDZ	-	6	26.6 X 13.2 X 11.8	135
	50	60	142	174	CFW-090142TDZ	(!)	7	32.9 X 13.2 X 11.8	172
	20	25	54	68	CFW-090054TDDBZ		4	18.7 X 9.8 X 10.8	55
	25	30	70	86	CFW-090070TDDBZ		5	21.6 X 13.2 X 10.8	101
	30	40	86	105	CFW-090086TDDBZ	YES	5	21.6 X 13.2 X 10.8	101
	40	50	105	130	CFW-090105TDDBZ		6	26.6 X 13.2 X 11.8	135
	50		130	150	CFW-090130TDDBZ		6	26.6 X 13.2 X 11.8	135
	50	60	142	174	CFW-090142TDDBZ	(!)	7	32.9 X 13.2 X 11.8	172
	60		180		CFW-090180TDZ	(!)	8	38.4 X 16.1 X 14.6	243
	75		240		CFW-090240TDZ	EXTERNAL**	8	38.4 X 16.1 X 14.6	243
						(!)	0	30.4 A 10.1 A 14.0	243
			Y: THREE PH						
	1 or 1.5			6	CFW-090003TGZ	_	1	8.3 x 5.6 x 7.7	9
		2			CFW-090004TGZ		1	8.3 x 5.6 x 7.7	9
	3		5.5		CFW-090005TGZ	_	1	8.3 x 5.6 x 7.7	9
	5		9		CFW-090009TGZ	- YES	1	8.3 x 5.6 x 7.7	9
	7.5		13		CFW-090013TGZ	-	2	11.4 x 7.2 x 7.7	15
	10		16 24		CFW-090016TGZ		2	11.4 x 7.2 x 7.7	15
	15				CFW-090024TGZ		2	11.4 x 7.2 x 7.7	15
	20	25	30	36	CFW-090030TGZ		3	15.3 x 8.9 x 10.8	46
	25	30	38	45	CFW-090038TGZ		4	18.7 x 9.8 x 10.8	55
	30	40	45	54	CFW-090045TGZ		4	18.7 x 9.8 x 10.8	55
	40	50	60	70	CFW-090060TGZ	NO USE CFW-09XXXTGDBZ	5	21.6 x 13.2 x 10.8	101
	50	60	70	86	CFW-090070TGZ	BELOW	5	21.6 x 13.2 x 10.8	101
	60	75	86	105	CFW-090086TGZ	_	6	26.6 x 13.2 x 11.8	135
	75	100	105	130	CFW-090105TGZ		6	26.6 x 13.2 x 11.8	135
	100	125	142	174	CFW-090142TGZ		7	32.9 x 13.2 x 12.2	172
	25	30 40	38 45	45	CFW-090038TGDBZ CFW-090045TGDBZ	-	4	18.7 x 9.8 x 10.8	55
	30 40	40 50	45 60	54 70	CFW-0900451GDBZ	-	4 5	18.7 x 9.8 x 10.8 21.6 x 13.2 x 10.8	55
	40 50	50 60	60 70	70	CFW-0900601GDBZ	YES	5		101
						160	-	21.6 x 13.2 x 10.8	
	60 75	75	86 105	105 130	CFW-090086TGDBZ CFW-090105TGDBZ	_	6 6	26.6 x 13.2 x 11.8 26.6 x 13.2 x 11.8	135
	100	125	105	130	CFW-0901051GDBZ	_	7	32.9 x 13.2 x 12.2	135
		-			CFW-0901421GDB2		8	38.4 x 16.1 x 14.6	243
	150 150		180 211		CFW-090180162	EXTERNAL**	8	38.4 x 16.1 x 14.6	243
	200		211 240		CFW-090211102		8	38.4 x 16.1 x 14.6	243
	200		312		CFW-090240102		9	39.4 x 27.5 x 19.3	529
	300		312		CFW-090361TGZ		9	39.4 x 27.5 x 19.3	529
	300		450		CFW-090361102		10	46.6 x 27.5 x 19.3	635
	400		450 515		CFW-0904501GZ	-	10	46.6 x 27.5 x 19.3	635
	500				CFW-0905151GZ	_	10	46.6 x 27.5 x 19.3	635
	* CT = Constant Torque: VT = Variable Torque		0111-030000102		10	40.0 X 27.3 X 19.3	030		
	** See Options ar (!) Non-Stocked I 1) "HP" rating ba 2) The 6, 7, and 1	id Accessorie tem, consult V sed on TABLE 0A/230V mod	s NEG for availabili 430 - 150NEC. A	LWAYS compare e-phase powere	e motor FLA to Nominal AMPS of drive. d without output current derating.				

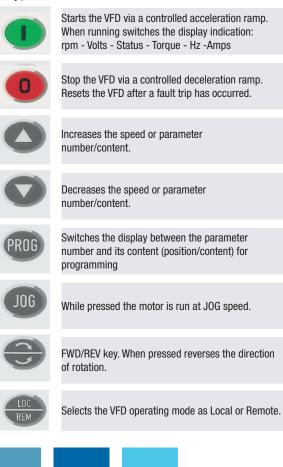


CFW09 Vectrue Inverter – A complete, flexible and compact product

Keypad



Keypad Functions



Intelligent Keypad

Intelligent operator interface with double display, LED (7 segment) and LCD (2 lines with 16 characters), providing optimum distant viewing along with a detailed description of all parameters and messages.

Selectable Language

The language of the LCD display messages can be selected by the operator. English, Spanish and Portuguese are available.

Oriented Start-up

The CFW09 "Oriented Start-up" feature was specially created to facilitate and expedite the start-up procedure. At the first power-up or after a reset to factory default parameters, an automatic programming routine guides the operator through a sequence of steps to plug in the minimum parameters necessary for a perfect relationship between drive and motor.

Copy Function

This intelligent keypad also incorporates a "Copy Function", which allows copying parameters from one drive to others, providing easy and reliable programming repeatability for duplicate applications. Keypad can store two complete sets of user parameters.



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Options and Accessories



External Braking Modules DBW Series



NEMA 4 Remote Keypad HMI – CFW09 – LCDN4

NEMA 4/IP55 remote keypad, for installation on panel door or remote operator station in harsh environments, such as splashing or hose-directed water and windblown dust. Maximum cable length: 33ft (10m)



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Remote Keypad Frame Kit KMR – CFW09

Frame for remote keypad mounting on panel door or operator station. Optional up to 15ft (5m) cable. Maximum cable length; 33 ft (10m)

Remote Keypad Cables CAB – HMI – 09 – X

Cables with lengths (x) of 3.3, 6.6, 10, ,15, 25 and 33ft (1, 2, 3, 5, 7.5 and 10m) 7.5 and 10m must use the KMRCFW09 frame kit. Special cables available upon request.

Remote Control Station-22mm CSW-SP3PBS

The remote control station is a 3-hole NEMA 4 pushbutton station with 22mm Start and Stop push buttons and a 5K potentiometer. Alternative configurations are available, consult factory for details.

Remote Control Station-30mm CSW30-SP3PBS

The remote control station is a 3-hole NEMA 4 pushbutton station with 30mm Start and Stop push buttons and a 5K potentiometer. Alternative configurations are available, consult factory for details. Alternative configurations are available, consult factory for details.



RS-232 Serial Interface KCS – CFW09

RS-232 Serial Interface Module to connect the CFW09 to a PC or other equipment via a RS-232 Serial Link, Profibus, Deuceuet Ethernet, Devicenet Profile communication.



PC Communication Kit KSD – CFW09

WEG Superdrive is a windows based software program that allows serial (RS-232 or RS-485) communication between a PC and WEG Soft Starters and Variable Frequency Drives. Superdrive is an excellent programming, documentation and troubleshooting tool for WEG Soft Starters and VFD's. Superdrive is available for free download at www.wegelectric.com. Hardware accessories may be required, depending on the Soft Starter or VFD line. Not available for SSW06.



PLC / Motion Control Board PLC 1.01 & PLC 2.00

PLC-01 / PLC-02 : WEG Integral PLC – The PLC01/02 boards add important PLC (Programmable Logical Controller) functions to the CFW-09, enabling the execution of complex logic program by using the digital and analog inputs and outputs as well as the digital and analog inputs and outputs of the own inverter which can be accessed by the user program. Functions include simple contacts and coils up to functions that uses floating point, such as sum, subtraction, multiplication, division, trigonometry, square root functions, etc. Other important functions are the PID blocks, high-pass and low-pass filters, saturation, comparison. All these functions operate with floating point. Besides the functions mentioned above, the PLC1 provides blocks for motor speed and motor position control, that is a trapezoidal-profile positioning and a S-profile positioning, speed reference generation with trapezoidal acceleration ramp, etc. (Note: when position functions used, the coupling of an encoder on motor shaft is required). All functions can interact with the user through the 100 programmable parameters that can be accessed directly through the inverter HMI. The texts and user units of the programmable parameters can be customized by the WLP.



Ethernet IP KFB - EN ProfiBus DP KFB - PD DeviceNet KFB - DN



I/O EXPANSION BOARDS EBA.0X - CFW09 EBB.0X - CFW09 EBC1.0X - CFW09 EBE.0X - CFW09

Configurations Functions	EBA			EBB				EBC			EBE	
	01	02	03	01	02	03	04	05	01	02	03	01
Encoder Input	•			•	•		•		•	•	•	
Encoder Output	•			•			•					
RS-485 Serial Interface	•	•		•			•					•
14 bit A/D	•		•									
14 bit D/A's	•		•									
Isolated Analog Input				•		•	•					
Isolated Analog Output				•		•	•	•				
Digital Inputs and Outputs Thermistor (PTC) Input	•	•	•	•	•	•	•					•
Internal Power Supply					•		•			•	•	

Technical Data

Power Supply	Voltage	Three Phase	220–230 V: 220 / 230 V (+10%, -15%) - 1 ø up to 3HP without de-ratin 380 - 480 V: 380 / 400 / 415 / 440 / 460 / 480 V (+10&, -15%)			
	Frequency	50 / 60 Hz +/- 2 Hz (4862 Hz)				
	Phase Unbalance Up to 3%					
	Cos (Displacement Power Factor)	Greater than 0.98				
Enclosure	Degree of Protection	NEMA 1 / IP 20 (sizes 1 to 8)				
		IP 20 (Sizes 9 and 10)				
	Finishing Color	Plastic Cover – Light Gray PANTONE 413C (sizes 1 and 2)				
		Metallic Cover and Sides – Light Gray RAL 7032 (sizes 3 to 10)				
		Base – Dark Gray RAL 7022 (sizes 3 to 10)				
Control	Power Supply	Switched Mode Power Supply Fed from the DC Link				
	Microprocessor	32 bit RISC Technology				
	PWM Technique	SVM Sine wave PWM (Space Vector Modulation)				
		Software Implemented Current, Flux and Speed Regulators (Full Digital) Scalar (Voltage Source – V/F)				
	Control Modes					
		Sensorless Vector (without encoder)				
		Flux Vector with Encoder				
	Switching Frequency	1.25 / 2.5 / 5.0 / 10 kHz				
	Frequency Range	0204 Hz for V / F and Vector with Encoder Control (60 Hz				
		0170 Hz for V / F and Vector with Encoder Control (50 Hz Motor)				
		0100 Hz for Sensorless Vector Control (50 or 60 Hz Moto	Sr)			
	Overload Capacity	150% for 60 seconds, every 10 minutes				
		180% for 1 second every 10 minutes				
<u> </u>	Efficiency	Greater than 97%				
Performance	Speed Control	V / F Mode	Regulation (with Slip Compensation) 1% of Motor Rated Speed			
			Resolution : 1 rpm (keypad reference) Speed Regulation Range : 20:1			
		Sensorless Vector Mode	Regulation : 0.5% of Motor Rated Speed			
			Resolution : 1 rpm (keypad reference)			
			Range : 100:1			
		Flux Vector Mode wih Encoder	Regulation with:			
			10 bit Analog Reference: +/- 0.1% of Motor Rated Speed			
			14 bit Analog Reference: +/- 0.01% of Motor Rated Speed1			
			Digital Reference (Ex: Keypad or Serial): +/- 0.01% of Motor Rated Speed Range : Down to 0 rpm			
	Torque Control	Flux Vector Modes	Regulation: +/- 10% of Motor Rated Torque Range : 0150% of Motor Rated Torque			
Control Inputs	Analog	2 Programmable Differential Inputs (10 bit) : 010 V, 020 mA or 420 mA				
	, individual of the second sec	1 Programmable Bipolar Input (14 bit) : -10+10 V, 020 mA or 420 mA				
		1 Programmable Bipolar Input (14 bit) : -10+10 V, 020 mA or 420 mA1 1 Programmable Isolated Input (10 bit) : 010 V, 020 mA or 420 mA1				
	Digital	6 Programmable Isolated Input : 24 Vdc				
	2.g.m.	1 Programmable Isolated Input : 24 Vdc 1				
		1 Programmable Isolated Input : 24 Vdc (for Motor PTC Thermistor) 1				
		I FIOGRAFIIIIADIE ISUIALEU IIIPUL . 24 VUC (IUI MULUI FIG IIIE	ermistor) 1			
	Encoder	1 Differential Input, with 12 Vdc Internal Isolated Power Su				
Control Outputs	Encoder Analog	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V				
Control Outputs		1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1	pply (14 bit resolution) 1			
Control Outputs	Analog	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4	pply (14 bit resolution) 1 20 mA 1			
Control Outputs		1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 V	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A			
Control Outputs	Analog Relay	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 V 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A			
Control Outputs	Analog Relay Transistor	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vac, 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1			
	Analog Relay Transistor Encoder	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vd 1 Programmable Output, Form A Contact (NO) : 240 Vdc, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdt 1 Isolated Differential Encoder Signals Output : 515 Vdc	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1			
	Analog Relay Transistor	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vd 1 Programmable Output, Form A Contact (NO) : 240 Vd 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1			
	Analog Relay Transistor Encoder	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vd 1 Programmable Output, Form A Contact (NO) : 240 Vdc, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdt 1 Isolated Differential Encoder Signals Output : 515 Vdc	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1			
Communication	Analog Relay Transistor Encoder Serial	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Va 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vac, 1 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage	pply (14 bit resolution) 1 20 mA 1 (ac, 1 A A A 5, 50 mA 1 External Power Supply 1			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 V 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Solated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1 External Power Supply 1 Output Short Circuit Output Ground Fault External Fault			
Control Outputs	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vd 1 Programmable Outputs, Form C Contacts (NO) : 240 Vd 1 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature Motor Over Temperature 1	pply (14 bit resolution) 1 20 mA 1 /ac, 1 A A c, 50 mA 1 External Power Supply 1 Output Short Circuit Output Short Circuit External Fault External Fault Self-diagnosis Fault			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (14 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 V 1 Programmable Outputs, Form C Contacts (NO/NC) : 240 V 1 Programmable Isolated Outputs (0pen Collector) : 24 Vdd 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature 1 Output Over Current	pply (14 bit resolution) 1 20 mA 1 (ac, 1 A A Comparison of the second secon			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240V 1 Programmable Outputs, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature Motor Over Temperature 1 Output Over Current Motor Overload (i x t)	pply (14 bit resolution) 1 20 mA 1 (ac, 1 A A A S, 50 mA 1 External Power Supply 1 Output Short Circuit Output Ground Fault External Fault Self-diagnosis Fault Programming Error Serial Communication Fault			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vac, 1 1 Programmable Outputs, Form A Contact (NO) : 240 Vac, 0 1 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature Motor Over Temperature 1 Output Over Current Motor Overload (i x t) Dynamic Braking Resistor Overload	pply (14 bit resolution) 1 20 mA 1 fac, 1 A A c, 50 mA 1 External Power Supply 1 Output Short Circuit Output Ground Fault External Fault External Fault Self-diagnosis Fault Programming Error Serial Communication Fault Motor or Encoder Connection Fault			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vac, 1 1 Programmable Outputs, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature 1 Output Over Current Motor Overload (i x t) Dynamic Braking Resistor Overload CPU / EPROM Error (Watchdog)	pply (14 bit resolution) 120 mA 1 fac, 1 A A A C C C C C C C C C C C C C C C C C			
Communication	Analog Relay Transistor Encoder Serial Field Bus Protections	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Va 1 Programmable Output, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 VdC 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature 1 Motor Over Temperature 1 Motor Over Current Motor Over Isolating Resistor Overload CPU / EPROM Error (Watchdog) Encoder Fault	pply (14 bit resolution) 120 mA 1 lac, 1 A A c, 50 mA 1 External Power Supply 1 Output Short Circuit Output Ground Fault External Fault Self-diagnosis Fault Programming Error Serial Communication Fault Motor or Encoder Connection Fault Power Supply Phase Fault (30 A and above models) Keypad Connection Fault			
Communication	Analog Relay Transistor Encoder Serial Field Bus	1 Differential Input, with 12 Vdc Internal Isolated Power Su 2 Programmable Outputs (11 bit) : 010 V 2 Programmable Bipolar Outputs (14 bit) : -10+10 V 1 2 Programmable Isolated Outputs (11 bit) : 020 mA or 4 2 Programmable Outputs, Form C Contacts (NO/NC) : 240 Vac, 1 1 Programmable Outputs, Form A Contact (NO) : 240 Vac, 1 2 Programmable Isolated Outputs (Open Collector) : 24 Vdc 1 Isolated Differential Encoder Signals Output : 515 Vdc RS-232 with KCS-CFW09 Kit 1 RS-485, Isolated, with EBA, EBE or EBB Board 1 Profibus DP, DeviceNet or Modbus RTU, with KFB kits 1 DC Link Over Voltage DC Link Under Voltage VFD Over Temperature 1 Output Over Current Motor Overload (i x t) Dynamic Braking Resistor Overload CPU / EPROM Error (Watchdog)	pply (14 bit resolution) 120 mA 1 lac, 1 A A c, 50 mA 1 External Power Supply 1 Output Short Circuit Output Ground Fault External Fault Self-diagnosis Fault Programming Error Serial Communication Fault Motor or Encoder Connection Fault Power Supply Phase Fault (30 A and above models) Keypad Connection Fault			



Data is subject to change without notice.

Technical Data

Conformities	EMC Directive 89 / 336/ EEC EN 61800-3	Electromagnetic Compatibility – Industrial Environment EMC - Emission and Immunity					
	LVC 73/23/EEC	Low Voltage Directive					
	IEC 146	Semiconductor Inverters					
	UL 508 C	Power Conversion Equipment					
	EN 50178	Electronic Equipment for use in power					
		installations					
	EN 61010	Saftey Requirements for Electrical Equipment for Mea-					
		surement, Control and Laboratory Use					
Certifications	UL (USA) and cUL (Canada)	Underwriters Laboratories Inc. USA					
ocruncations	CE (Europe)	Phoenix Test - Labs GmbH - Germany					
Koypad	Programming	General VFD Functions Programming					
Keypad	Commands	Start / Stop, Increase / Decrease Speed, JOG, FWD/REV and	L local/Remote				
	Monitoring	Speed Reference (rpm)	Output Current (A)				
	lineinennig	Motor Speed (rpm)	Output Voltage (Vac)				
		Speed Proportional Value (Ex: ft/min)	VFD Status				
		Output Frequency (Hz)	Digital Inputs Status				
		DC Link Voltage (Vdc)	Transistor Outputs Status				
		Motor Torque (%)	Relay Outputs Status				
		Output Power (kW)	Analog Inputs Value				
		Hours Powered Up (h)	Four Last Faults				
		Hours Enabled (h)	Fault Messages				
Control Features	Standard	Keypad with LCD + LED displays (HMI:-CFW09-LCD)					
and Options		Password to protect VFD programming					
		LCD display language selection: English, Spanish and Portuguese					
		Control mode selection (via parameter): V / F, Sensorless Vector or Vector with Encoder					
		Fault auto-diagnosis and auto-reset					
		Parameters reset to factory or user default					
		VFD Self-tning to motor and load (Vector Modes)					
		Specific unit indication (Ex: I/s, th, %, etc)					
		Motor slip compensation (V / F Mode)					
		Manual and automatic Torque Boost (V / F Mode)					
		Adjustable V / F Curve (V / F Mode)					
		Minimum and maximum speed limits					
		Output current limit Adjustable motor overload protection					
		Digital gain and offset adjustments for the analog inputs					
		Digital gain and onset adjustments for the analog inputs Digital gain adjustments for the analog outputs					
		JOG function					
		JOG +/ JOG - function (momentary speed increase/decrease, phase shift)					
		COPY function (VFD / Keypad or Keypad / VFD)					
		Comparison functions for the digital outputs:					
		N*> Nx; N> Nx; N < Nx; N = 0; N = N*; Is > Ix; Is < Ix; T > Tx and T < Tx					
		Where: N = Motor speed; N [*] = Speed reference is; Is = Output current and T = Motor torque					
		Linear and S independent acceleration and deceleration ramps, two sets of ramps					
		DC Braking					
		Optimal Braking™ (Vector Modes)					
		Built-in dynmanic braking transistor - Models up to 45A / 220-230V and 30A / 380-480V					
		Multi-speed function (up to 8 preset speeds)					
		Speed Profiling function					
		Hour meter and Wattmeter PID regulation (for automatic control of level, pressure, flow, etc.)					
		FWD / REV selection					
		Local / Remote operation selection					
		Flying start function (restart with the motor spinning)					
		Skip speed (critical speed rejection)					
		Ride-through (operation during momentary power loss)					
		Built-in dynamic braking transistor: Models 6 45A / 220-230V and 3.6 30A / 380 -480V					
	Ontions		avnad for local installation				
	Options	Remote keypad cable (3.3, 6.6, 10, 16, 25 and 35ft) Blank k					
	Options						







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